



The Pareto Grid in Multiparameter Persistence

Based in joint work with F. Conti, P. Frosini, U. Fugacci, N. Quercioli,
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Introduction

1 Introduction

- Let M be a closed smooth Riemannian manifold of dimension ≥ 2 .
- Consider a smooth function $\varphi = (\varphi_1, \varphi_2): M \rightarrow \mathbb{R}^2$.
- Taking the homology of the sublevel sets of φ yields a biparameter persistence module.



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- Taking the homology of the sublevel sets of φ yields a biparameter persistence module.
- **Obstruction:** There is no complete invariant for n -parameter persistence for $n \geq 2$.
- **Strategy:** "Slice" the biparameter module with a suitable family of monoparameter modules.



1-parameter "slice" of a filtration

1 Introduction

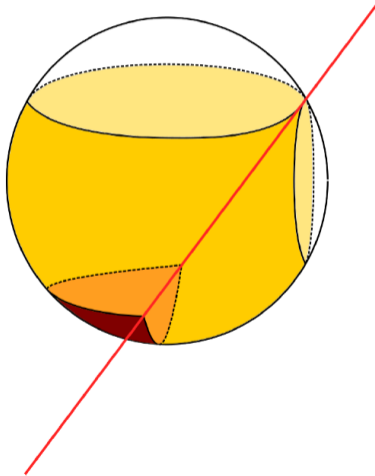




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Pareto Critical points

2 The Pareto Grid

Definition: Jacobi set

The Jacobi set, $\mathbb{J}(\varphi)$, is the set of points $x \in M$ at which the gradients $\nabla\varphi_1(x)$ and $\nabla\varphi_2(x)$ are parallel.

$$\exists(\lambda_1, \lambda_2) \neq (0, 0) \text{ s.t. } \lambda_1 \nabla\varphi_1(x) + \lambda_2 \nabla\varphi_2(x) = 0$$



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Pareto-critical set

The Pareto critical set, $\mathbb{J}_P(\varphi)$, is the subset of $\mathbb{J}(\varphi)$ consisting of points $x \in M$ at which the gradients $\nabla\varphi_1(x)$ and $\nabla\varphi_2(x)$ are parallel and of opposing direction.

$$\exists\lambda_1, \lambda_2 \geq 0 \text{ s.t. } \lambda_1 \nabla\varphi_1(x) + \lambda_2 \nabla\varphi_2(x) = 0$$



Pareto Critical points

2 The Pareto Grid

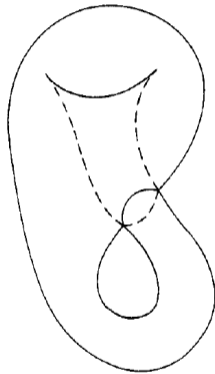


Fig. 1

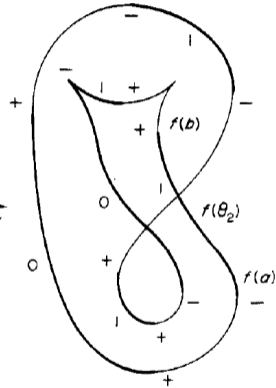


Fig 2

Figure: Image courtesy of [Wan'75]



Generic assumptions

2 The Pareto Grid

Assume φ satisfies the following:

- No point $x \in M$ exists where both $\nabla\varphi_1(x)$ and $\nabla\varphi_2(x)$ vanish simultaneously.



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- The set of cusp points $\mathbb{J}_C(\varphi)$ splits $\mathbb{J}_P(\varphi)$ into finitely many connected components diffeomorphic to intervals. With respect to any parametrization, one component of φ is decreasing and the other one is increasing along these connected components.



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These assumptions are generic on the set of smooth functions $M \rightarrow \mathbb{R}^2$ [Wan'75, EH'04].



The Pareto Grid

2 The Pareto Grid

Definition: Pareto Grid

The Pareto grid $\Gamma(\varphi)$ of φ is the image of the Pareto-critical points $\varphi(\mathbb{J}_P(\varphi)) \subset \mathbb{R}^2$.

Definition: Extended Pareto Grid

Let $\{(x_i^1, y_i^1)\}_i$ and $\{(x_j^2, y_j^2)\}_j$ denote the (finite) critical points of φ_1 and φ_2 , respectively. The Extended Pareto grid $\bar{\Gamma}(\varphi)$ consists of the union

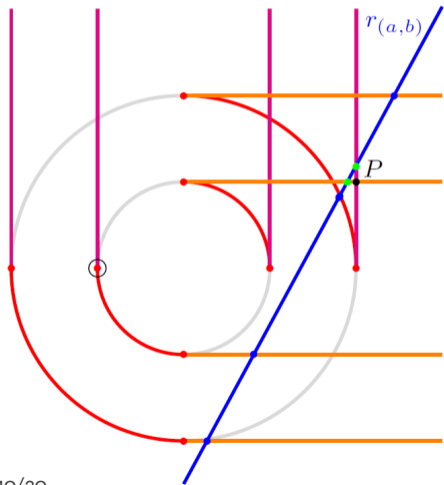
$$\bar{\Gamma}(\varphi) = \Gamma(\varphi) \cup \bigcup_i v_i \cup \bigcup_j h_j,$$

where $v_i = \{(x_i^1, y) \mid y \geq y_i^1\}$ and $h_j = \{(x, y_j^2) \mid x \geq x_j^2\}$.



The Pareto Grid

2 The Pareto Grid



Contours

The closures of the connected components of $\mathbb{J}_P(\varphi) \setminus \mathbb{J}_C(\varphi)$ under φ are called *proper contours*. The half-lines in $\bar{\Gamma}(\varphi)$ are the *improper contours*.



Interesting properties of the Pareto Grid

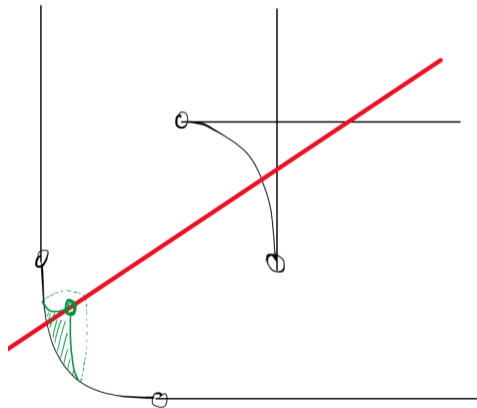
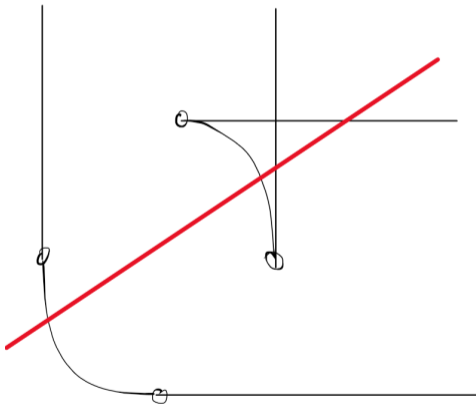
2 The Pareto Grid

- **Finiteness:** The number of contours is finite.
- **Unique Intersections:** Because filtering lines $r_{(a,b)}$ always have a strictly positive slope, their intersection with any contour is either empty or exactly a single point.



A badly drawn example

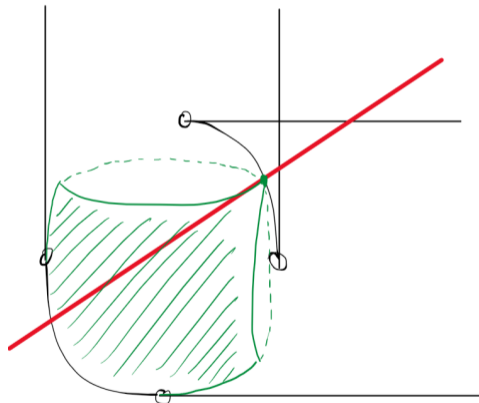
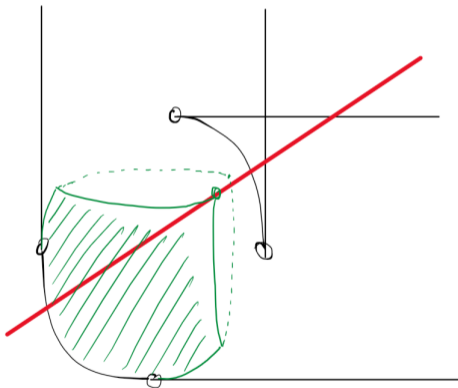
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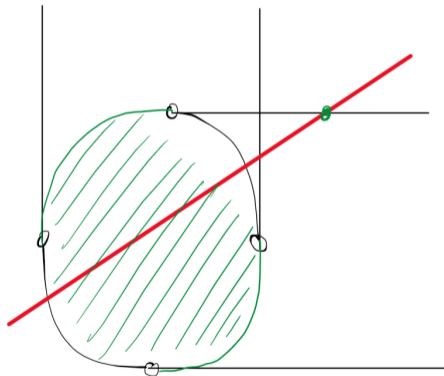
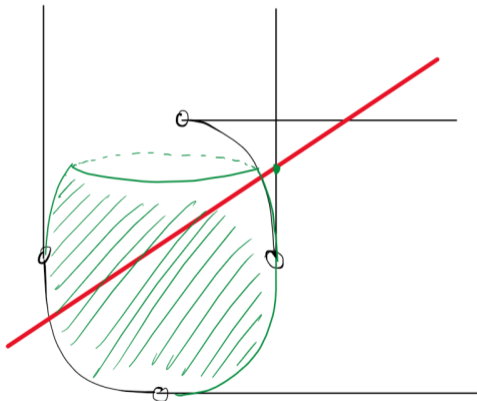
2 The Pareto Grid





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2 The Pareto Grid





A properly drawn example

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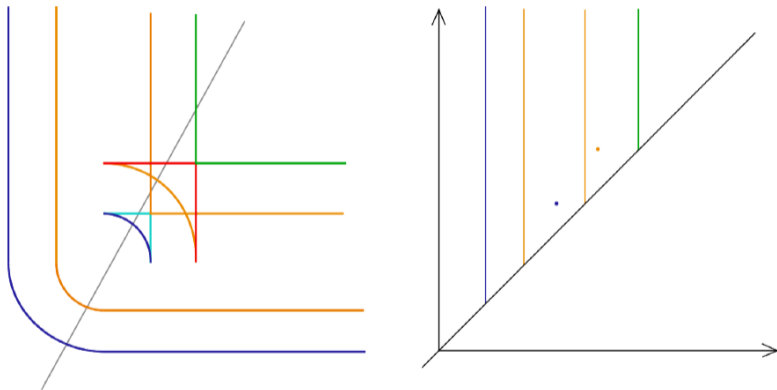


Figure: The Pareto grid of the projection of a torus together with the corresponding persistent diagram(s).



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1-Parameter Reductions: GENEOS [Fro'16]

3 Distances and GENEOS

Given a set X let $\Phi \subset \{X \rightarrow \mathbb{R}^k\}$ and $G < \text{Homeo}(X)$ acting on Φ by right composition. The pair (Φ, G) is called a perception pair.

Consider two perception pairs (Φ, G) and (Ψ, H) and fix a homomorphism $T: G \rightarrow H$. A *Group Equivariant Non Expansive Operator (GENEO)* is a function $F: \Phi \rightarrow \Psi$ such that:

- $F(\varphi \circ g) = F(\varphi) \circ T(g)$,
- $D_\Psi(F(\varphi), F(\varphi')) \leq D_\Phi(\varphi, \varphi')$.



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Given a parametrized family of GENEOS $\mathcal{F} = \{F_\theta\}_\theta$ one can define:

$$D_{\mathcal{F}}(\varphi, \psi) = \sup_{\theta} d_B(Dgm_k(F_\theta(\varphi)), Dgm_k(F_\theta(\psi))).$$



1-Parameter Reductions

3 Distances and GNEOs

Stability [BFGQ'19]

$D_{\mathcal{F}}$ is stable w.r.t. the supremum norm $\|\cdot\|_{\infty}$.



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Two examples with $\Phi \subset (\mathbb{R}^2)^X$, $G, H = 0$ and T the identity homomorphism:



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Two examples with $\Phi \subset (\mathbb{R}^2)^X$, $G, H = 0$ and T the identity homomorphism:

1. Foliation Method (Classical Matching Distance MD):

For $(a, b) \in]0, 1[\times \mathbb{R}$:

$$\varphi_{(a,b)}^*(\mathbf{x}) = \min\{a, 1 - a\} \max\left\{\frac{\varphi_1(\mathbf{x}) - b}{a}, \frac{\varphi_2(\mathbf{x}) + b}{1 - a}\right\}.$$



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2. Convex combination (Convex Matching Distance CMD):

For $t \in [0, 1]$:

$$\varphi^t(x) = (1 - t)\varphi_1(x) + t\varphi_2(x).$$



Advantages of the CMD

3 Distances and GNEOs

- **Differentiability Preservation:** For each t , $\varphi \mapsto \varphi^t$ preserves the smoothness of the original functions. In contrast, the \min / \max operators in $\varphi_{(a,b)}^*$ only preserve continuity.
- **Dimensionality Reduction:** CMD is defined via a 1-parameter family.



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Position Theorems

4 Position Theorems

Position Theorem (MD) [CEF'19]

Let $(a, b) \in]0, 1[\times \mathbb{R}$ and let w be a finite coordinate of a point in $Dgm_k(\varphi_{(a,b)}^*) \setminus \{\Delta\}$.

Then there exists a point $P = (x, y) \in r_{(a,b)} \cap \bar{\Gamma}(\varphi)$ such that:

- $w = \min \left\{ 1, \frac{1-a}{a} \right\} (x - b)$ if $a \in [0, 1[$
- $w = \min \left\{ 1, \frac{a}{1-a} \right\} (y + b)$ if $a \in]0, 1]$

Geometric Intuition: The finite coordinates of the diagram are found by intersecting the filtering line $r_{(a,b)}$ with the Extended Pareto Grid $\bar{\Gamma}(\varphi)$, and then applying a scaling factor that depends on the slope of the line.



Position Theorems

4 Position Theorems

Position Theorem (CMD) [CFFMQST'26]

Let $t \in [0, 1]$ and let w be a finite coordinate of a point in $Dgm_k(\varphi^t) \setminus \{\Delta\}$. Then there exist a contour $\alpha : [0, 1] \rightarrow \mathbb{R}^2$ and a $\bar{\tau} \in [0, 1]$ such that:

1. $\alpha(\bar{\tau}) \cdot (1 - t, t) = w$
2. $\frac{d\alpha}{d\tau}(\bar{\tau}) \cdot (1 - t, t) = 0$

Geometric Intuition: The finite coordinates of the diagram are found by taking lines with direction $(1 - t, t)$ and finding where they intersect the contours orthogonally.



Proof Sketch of the Position Theorem (CMD)

4 Position Theorems

- **Step 1:** Since w is a finite coordinate in the persistence diagram $Dgm_k(\varphi^t)$, w is a critical value for φ^t .



Proof Sketch of the Position Theorem (CMD)

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- **Step 3:** Expanding the gradient gives $(1 - t)\nabla \varphi_1(\bar{x}) + t\nabla \varphi_2(\bar{x}) = 0$, proving \bar{x} is a Pareto critical point of φ . Let $\alpha(\bar{\tau}) = \varphi(\bar{x})$. Thus $w = \alpha(\bar{\tau}) \cdot (1 - t, t)$.



Proof Sketch of the Position Theorem (CMD)

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- **Step 4:** For a regular parametrisation γ of α , we have $0 = \nabla \varphi^t(\bar{x}) \cdot \frac{d\gamma}{d\tau}(\bar{\tau})$. Applying the chain rule, this becomes $\frac{d\alpha}{d\tau}(\bar{\tau}) \cdot (1 - t, t) = 0$.



Special Values

4 Position Theorems

- The Position Theorem(s) translate the computation of MD (CMD) into tracking the intersections between filtering lines and $\bar{\Gamma}(\varphi)$ ($\Gamma(\varphi)$, respectively).
- **Obstruction:** The matching realizing the Bottleneck distance is not continuous with respect to θ .

Special values

The sudden shifts in the optimal matching occur at a privileged subset of parameters θ . To compute the distance, we can restrict our search to the **special set** $Sp(\varphi, \psi)$.



Special values

4 Position Theorems

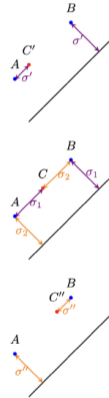
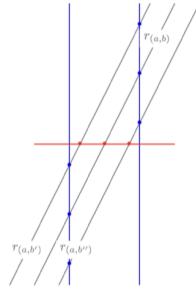


Figure: A configuration on $\bar{\Gamma}(\varphi)$ corresponding to a special value.



Main Theorems: Realizing the Distances

4 Position Theorems

Theorem for MD [EFQT'23],[FMQT'25]

If (a, b) realises $\text{MD}(\varphi, \psi)$, then either $a = \frac{1}{2}$ or $(a, b) \in \text{Sp}^{\text{MD}}(\varphi, \psi)$.

Theorem for CMD [CFFMQST'26]

If t realises $\text{CMD}(\varphi, \psi)$, then either $t \in \text{Sp}^{\text{CMD}}(\varphi, \psi)$.



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Conclusions and Future Directions

5 Conclusion

Summary

- The **Pareto grid** is a partial invariant of filtrations arising from \mathbb{R}^2 -valued functions closely related to its associated monoparametric filtrations.
- This relation is explicated via the Position theorem, allowing computation.

Open Problems

- Identify the minimal hypothesis under which the special set $Sp(\varphi, \psi)$ is generically.
- Develop and optimize algorithmic implementations that exploit the Special set set to compute the MD/CMD efficiently.



Bibliography

5 Conclusion



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Backup: The Special Set for MD

5 Conclusion

Definition [FMQT'25]

The special set $Sp(\varphi, \psi)$ for the MD is the collection of all (a, b) in $]0, 1[\times \mathbb{R}$ for which there exist two different pairs of contours $\{\alpha_P, \alpha_Q\}, \{\alpha_R, \alpha_S\}$ in $Ctr(\varphi, \psi)$ intersecting the line $r_{(a,b)}$ at points P, Q, R, S respectively, such that:

Case 1 ($a \leq 1/2$):

$$c_1|x_P - x_Q| = c_2|x_R - x_S| \quad \text{with } c_1, c_2 \in \{1, 2\}$$

Case 2 ($a \geq 1/2$):

$$c_1|y_P - y_Q| = c_2|y_R - y_S| \quad \text{with } c_1, c_2 \in \{1, 2\}$$

Intuition: The bottleneck distances associated with distinct pairs of homological features become proportional, causing a tie in the optimal matching.



Backup: The Special Set for CMD

5 Conclusion

Definition [CFFMQST'25]

The special set $Sp(\varphi, \psi)$ for CMD consists of values $t \in [0, 1]$ satisfying at least one of the following:

1. A line with direction $(1 - t, t)$ intersects a contour orthogonally at one of its endpoints.
2. Lines r_i intersect contours α_i orthogonally at P_i ($i \in \{1, 2, 3, 4\}$) such that:

$$(P_1 - P_2) \cdot (1 - t, t) = c((P_3 - P_4) \cdot (1 - t, t)), \quad c \in \{1, 2\}$$

3. Orthogonal intersections P_1, P_2 exist where either a contour has zero curvature, their signed radii l_1, l_2 are equal, or t satisfies:

$$t = \frac{\zeta}{1 + \zeta} \quad \text{with} \quad \zeta = \tan \left(\frac{1}{2} \arcsin \left(1 - \left(\frac{(y_1 - y_2) - (x_1 - x_2)}{l_1 - l_2} \right)^2 \right) \right)$$